

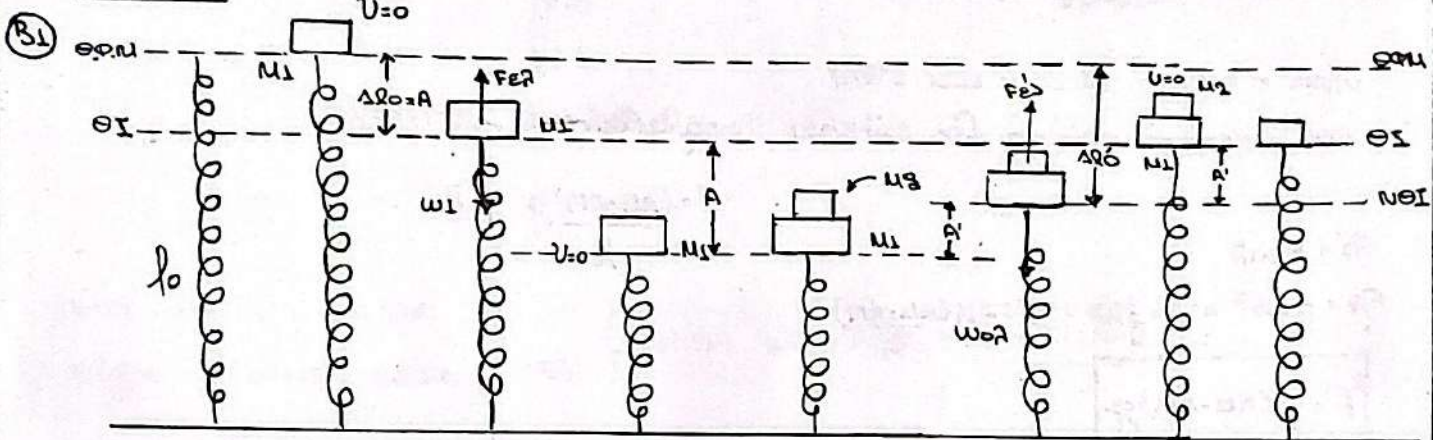
ΔΙΑΓΩΝΙΣΜΑ ΤΑΝΑΝΤΟΣΕΙΣ ΙΑΝΟΥΑΡΙΟΣ 2005

ΘΕΜΑ Α

$A_1 \rightarrow \gamma$ $A_2 \rightarrow \delta$ $A_3 \rightarrow \epsilon$ $A_4 \rightarrow \delta$

$A_5 \rightarrow \alpha-\delta, \epsilon-\lambda, \gamma-\delta, \delta-\delta, \epsilon-\delta$

ΘΕΜΑ Β



B1a | ΘΙ: $\sum F = 0 \Rightarrow F_{12} = m_1 g \Rightarrow k \Delta l_0 = m_1 g = 2mg$

$\Delta l_0 = 2mg/k$ και $A = 2mg/k$ (1)

ΝΘΙ: $\sum F = 0 \Rightarrow F'_{12} = m_2 g \Rightarrow k \Delta l'_0 = (m_1 + m_2)g \Rightarrow$

$\Delta l'_0 = \frac{(2m + m)g}{k} \Rightarrow \Delta l'_0 = \frac{3mg}{k}$ (2)

$A' = \Delta l'_0 - \Delta l_0 = 3mg/k - 2mg/k = mg/k$ (3)

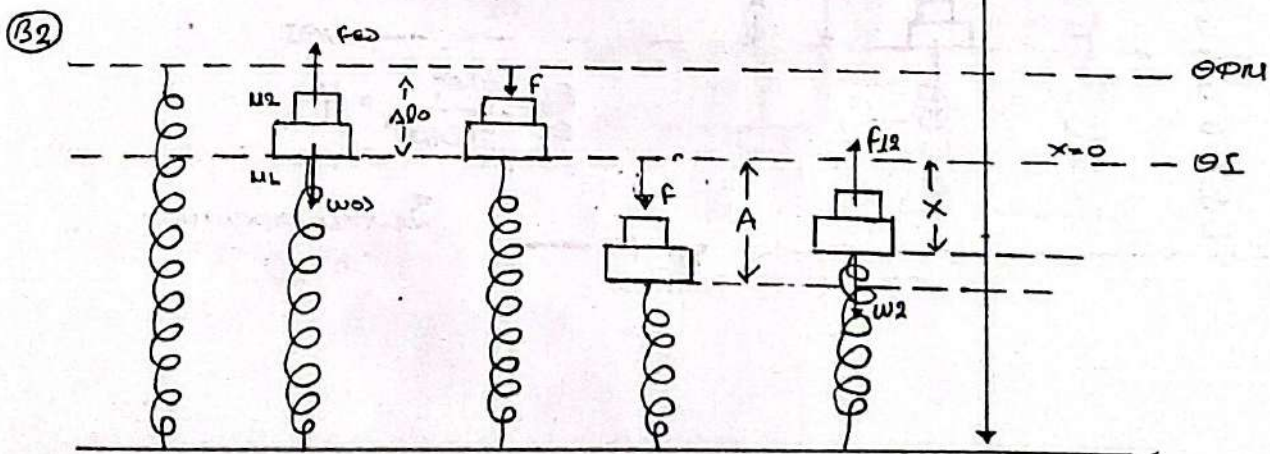
$S_1 = 2A = 2 \cdot 2mg/k = 4mg/k$ (4)

$S_2 = 2A' = 2mg/k$ (5)

(4), (5) $\frac{S_1}{S_2} = 2$ (6)

Σωστός εντοπί η α

B1b | Σωστός η β



$$\textcircled{\Theta I} \quad \sum F = 0 \Rightarrow K \Delta l_0 = (m_1 + m_2)g \quad \textcircled{1}$$

$$\sum F_2 = -D_2 x \Rightarrow W_2 - F_{12} = -D_2 x \quad \textcircled{2}$$

$$W_2 + D_2 x = F_{12} \quad \text{Η επαφή χάνεται και θέρει όπου } F_{12} = 0 \Rightarrow W_2 + D_2 x = 0$$

$$x = -\frac{W_2}{D_2} \quad \text{αλλά (με αποδόξιν)} \quad D_2 = \frac{m_2 k}{m_1 + m_2}$$

$$\text{Άρα, } x = -\frac{m_2 g}{\frac{m_2 k}{m_1 + m_2}} = -\frac{(m_1 + m_2)g}{k} = -\Delta l_0 \quad \textcircled{3}$$

Άρα η επαφή χάνεται και θέρει

και η επαφή οριστικά δεν χάνεται καταβαλίνουμε ότι $A = \Delta l_0$

$$A = \frac{(m_1 + m_2)g}{k} \quad \textcircled{4}$$

$$F_A = E_{\text{ελατ}}$$

$$F_A = \frac{1}{2} k A^2 \Rightarrow F = \frac{1}{2} k A \Rightarrow F = \frac{1}{2} k \frac{(m_1 + m_2)g}{k}$$

$$F = \frac{1}{2} (m_1 + m_2)g$$

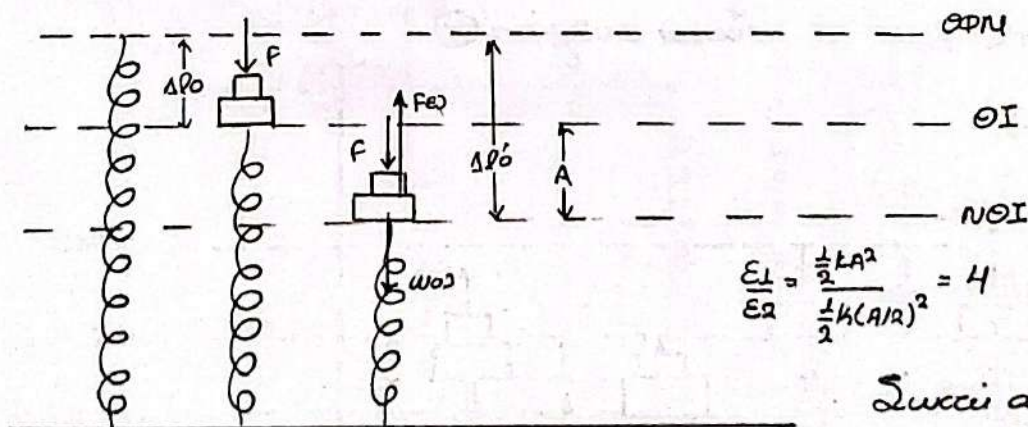
Όταν η F δρά μόνιμα και δεν αποσύρεται τότε η ταλάντωση γίνεται γύρω από το ΝΘΙ στην οποία

$$F + W_{02} = F'_{\text{ελ}} \Rightarrow \frac{1}{2} (m_1 + m_2)g + (m_1 + m_2)g = k \Delta l'_0$$

$$\frac{3}{2} (m_1 + m_2)g = k \Delta l'_0 \Rightarrow \Delta l'_0 = \frac{3}{2} \frac{(m_1 + m_2)g}{k}$$

Και το ηλίκος της ταλάντωσης

$$\text{Είρην } A' = \Delta l'_0 - \Delta l_0 = \frac{1}{2} \left(\frac{m_1 + m_2}{k} \right) g = \frac{A}{2} \quad \textcircled{5}$$

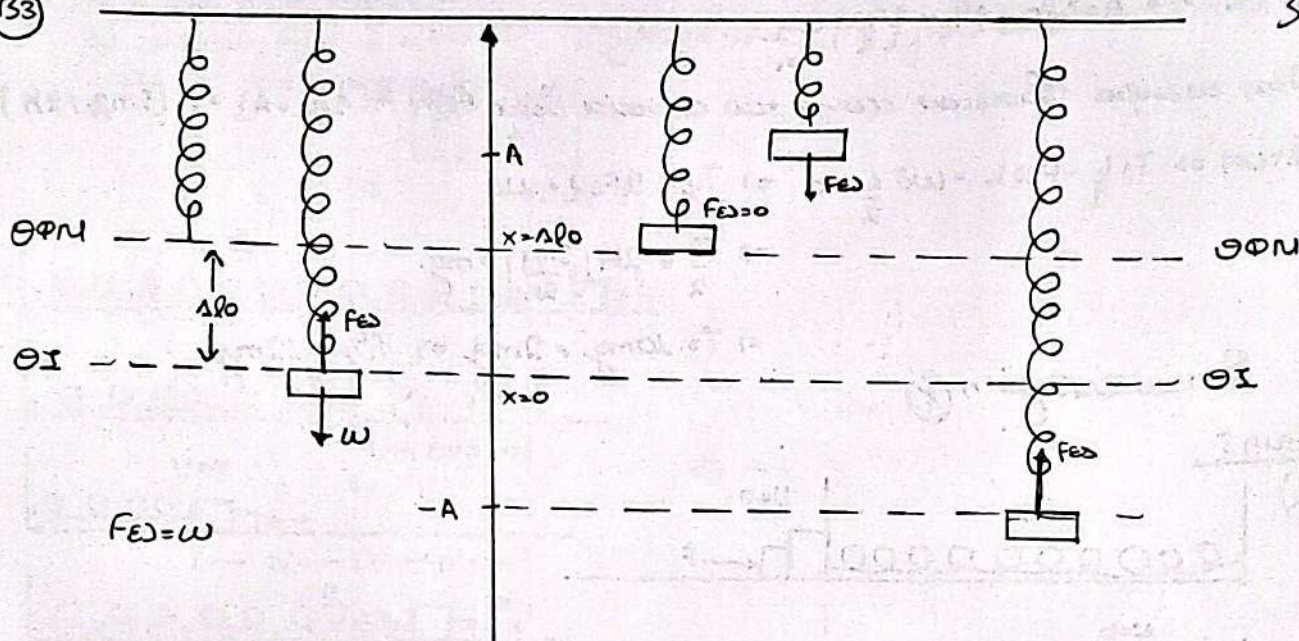


$$\frac{E_1}{E_2} = \frac{\frac{1}{2} k A^2}{\frac{1}{2} k (A/2)^2} = 4$$

Σωστή απάντηση
η $\textcircled{B}$

33

3



$$x=0 \quad F_s=W \Rightarrow W=10 \text{ N} \quad (1)$$

$$x=\frac{1}{15} \text{ m}, \quad F_s=0, \quad \Delta l_0=\frac{1}{15} \quad (2)$$

$$\left. \begin{array}{l} (1), (2) \end{array} \right\} k \Delta l_0 = 10 \Rightarrow \boxed{k=150 \text{ N}} \quad (3)$$

$$x=A \quad F_s=-50 \text{ N}, \quad -k \Delta l_0 = -50$$

$$k \Delta l_0 = 50 \Rightarrow k(A - \Delta l_0) = 50$$

$$A - \frac{1}{15} = \frac{50}{150} \Rightarrow A = \frac{1}{3} + \frac{1}{15} \Rightarrow A = \frac{5}{15} + \frac{1}{15} = \frac{6}{15}$$

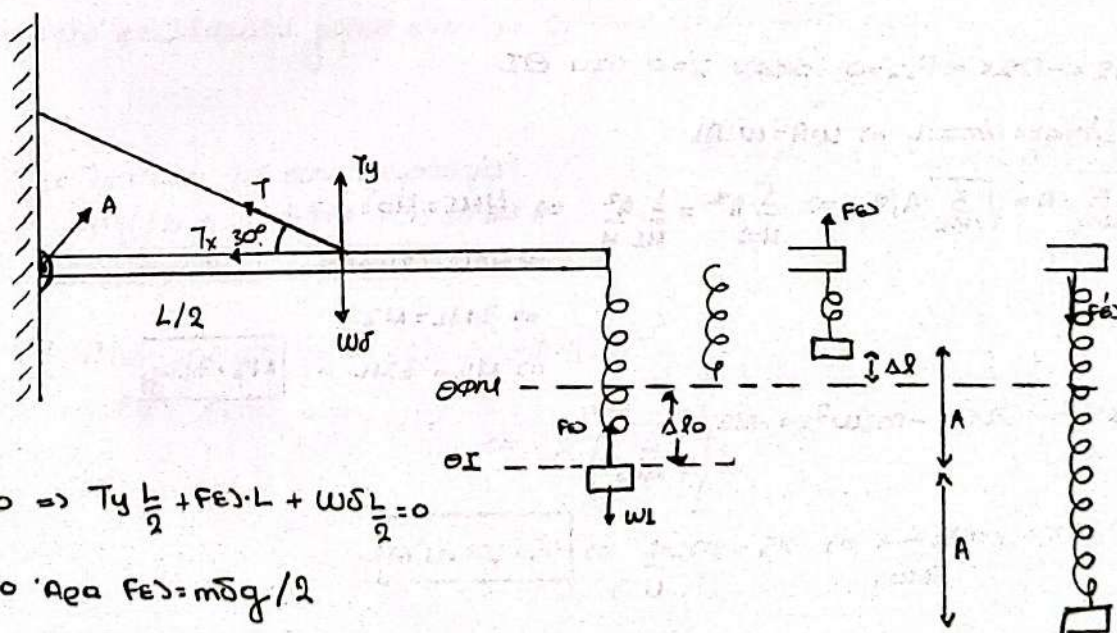
$$\boxed{A=0,4 \text{ m}} \quad (4)$$

$$E_{\text{pot}} = \frac{1}{2} k A^2 = \frac{1}{2} 150 \cdot 0,16 \Rightarrow$$

$$E_{\text{pot}} = 12 \text{ J}$$

Σωστή επιλογή η β

34



$$\Sigma \tau(A) = 0 \Rightarrow T_y \frac{L}{2} + F_s \cdot L + W \delta \frac{L}{2} = 0$$

$$T_{0\theta} = 0 \quad \text{Αρα } F_s = m \delta g / 2$$

$$k \Delta l = m \delta g / 2 \Rightarrow \Delta l = mg / 2k \quad (1)$$

(1), (2) $\rightarrow A = \Delta l_0 + \Delta l = \left(\frac{3}{2}\right) \frac{mg}{k}$

Όταν το σώμα βρίσκεται στην κάτω ακραία θέση $F_{\epsilon\lambda} = k(\Delta l_0 + A) = k(5mg/2k)$

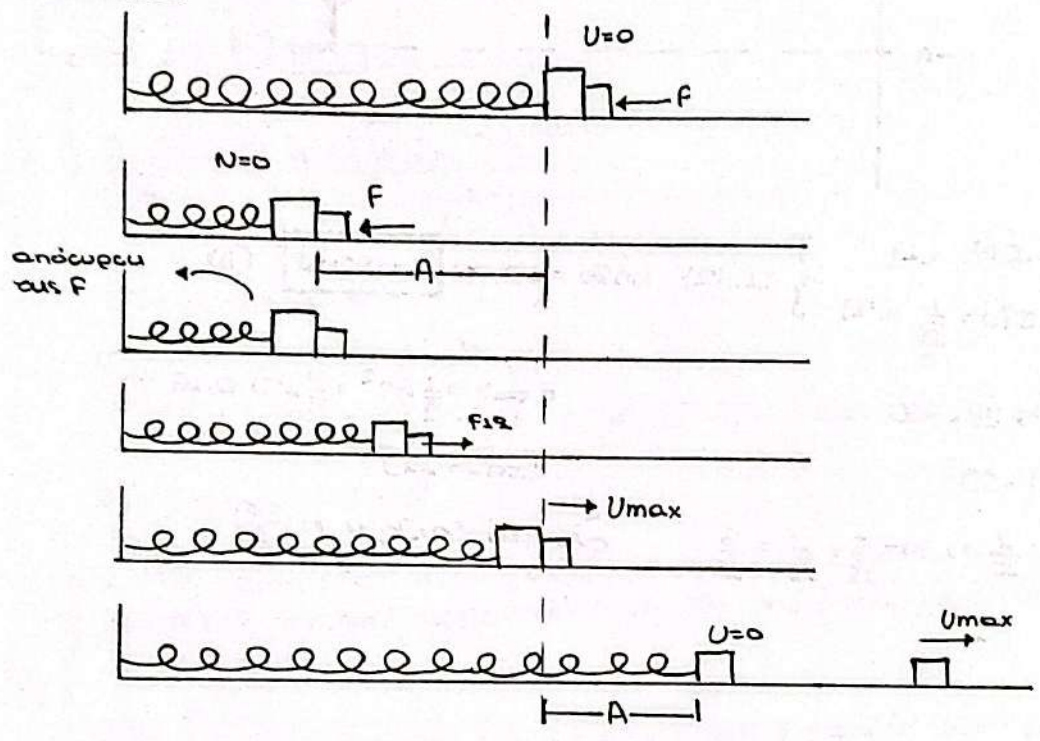
$\sum \tau(A) \Rightarrow T_y \frac{L}{2} - F_{\epsilon\lambda} L - \omega \delta \frac{L}{2} = 0 \Rightarrow T_y = 2F_{\epsilon\lambda} + \omega \delta$

$\Rightarrow \frac{T}{2} = 2k\left(\frac{5mg}{2k}\right) + mg$

$\Rightarrow T = 10mg + 2mg \Rightarrow T_{\rho} = 12mg$

Σωστί επιλογή η $\oplus$

ΘΕΜΑ Γ



(Γ1) $F_{12} = -Dx$ $F_{12} = 0$ όταν $x = 0$ και Θ1

$U_{max} = U_{maxL} \Rightarrow \omega A = \omega |A|$

$\sqrt{\frac{k}{m_0}} \cdot A = \sqrt{\frac{k}{m_L}} \frac{A}{2} \Rightarrow \frac{1}{m_0} A^2 = \frac{1}{m_L} \frac{A^2}{4} \Rightarrow 4m_L = m_0$

$\Rightarrow 4m_L = m_1 + m_2$

$\Rightarrow 3m_L = m_2$

$\Rightarrow m_2 = 3m_L \Rightarrow \boxed{m_2 = 3kg}$

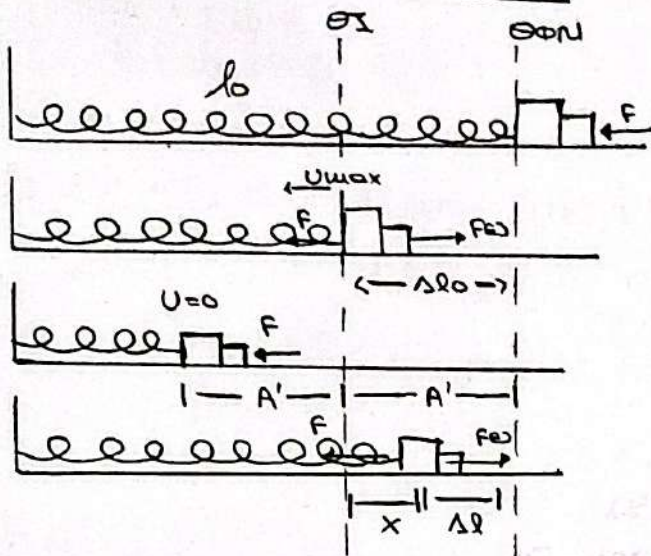
(Γ2) $F_{12} = -Dx = -m_2 \omega^2 x = -m_2 \left(\sqrt{\frac{k}{m_0}}\right)^2 x \Rightarrow$

$-75x = -m_2 \frac{k}{m_0} x \Rightarrow 75 = m_2 \frac{k}{m_0} \Rightarrow \boxed{k = 1000 N/m}$

Γ3

Για όση ώρα ασκεύου η $\vec{F}$
το σύστημα των 2 σωμάτων πραγματοποιεί ΑΑΤ γύρω από
τη ΘΣ στην οποία $F = F_{\text{ελ}} \Rightarrow$

$$F = k \Delta l_0$$



$$\Sigma F = -F + F_{\text{ελ}} \Rightarrow$$

$$-F + k \Delta l = -F + k (\Delta l_0 - x)$$

$$= -F + k \Delta l_0 - kx = -kx \Rightarrow \Omega = \Omega_0 \text{ Άρα } v_{\text{max}} = \omega A' = \sqrt{\frac{k}{m}} A'$$

$$A' = 0,2 \text{ m} \text{ άρα } A = 2A'$$

Διότι η F αποσύρεται στην αριστερή οκράια θέσι οπότε στη στιγμή
η ταλάντωση γίνεται χωρίς την παρουσία της F και γύρω από τη ΘΦΝ

$$\text{Άρα } A = 2A' = 0,4 \text{ m}$$

και για την ταλάντωση γύρω από τη ΘΦΝ έχουμε $(W F = E_{\text{τα}}) \Rightarrow$

$$F A = \frac{1}{2} k A^2 \Rightarrow$$

$$F = \frac{1}{2} k A \Rightarrow F = \frac{1}{2} 100 \cdot 0,4 = 20 \text{ N}$$

$$F = 20 \text{ N}$$

Γ4

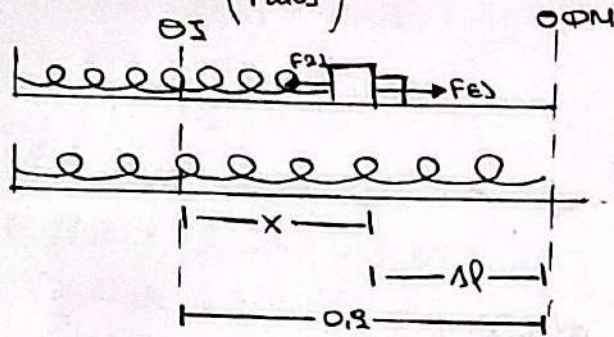
Η ταλάντωση με την παρουσία
της F αρχίζει στη ΘΦΝ που είναι η
δεξιά οκράια θέσι της ταλάντωσης

$$\text{Άρα, } x = A \sin(\omega t + \varphi_0) = 0,2 \sin(5t + \pi/2) \text{ SI}$$

$$\text{καθώς } t=0, x=A, v=0$$

$$\textcircled{75} \quad F_{q1} = -D_1 x = -M_1 \omega^2 x \Rightarrow$$

$$F_{q1} = -1 \left(\sqrt{\frac{k}{m \omega_0}} \right)^2 x = -25x$$



$$F_{e1} - F_{q1} = -25x \Rightarrow$$

$$F_{e1} + 25x = F_{q1} \Rightarrow$$

$$k \Delta l + 25x = F_{q1} \Rightarrow k(0.2 - x) + 25x = F_{q1}$$

$$\Rightarrow 100 \cdot 0.2 - 100x + 25x = F_{q1}$$

$$\Rightarrow 20 - 75x = F_{q1}$$

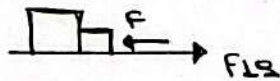
$$F_{q1 \max} \text{ at } x = -A'$$

$$F_{q1 \max} = 20 - 75(-0.2) \Rightarrow$$

$$F_{q1 \max} = 20 + 15 = 35 \text{ N} \Rightarrow$$

$$\boxed{F_{q1 \max} = 35 \text{ N}}$$

$$n \quad F_{q1 \max} = F_{q2 \max}$$



$$SF_2 = -D_2 x \Rightarrow$$

$$SF_2 = -75x \Rightarrow$$

$$F_{12} - F = -75x \Rightarrow F_{12} = F - 75x$$

$$\Rightarrow F_{12 \max} = 20 - 75(-0.2) = 35 \text{ N}$$

ΘΕΜΑ Δ

7

$$\Delta 1) \vec{p}_{0\lambda, \sigma\rho\lambda} = \vec{p}_{0\lambda, \tau\epsilon\lambda}$$

$$m_1 u_1 = m_1 u_1' + m_2 u_2'$$

$$1 \cdot u_1 = 1 \cdot u_1' + 2 \cdot 2$$

$$u_1 = u_1' + 4 \quad (1)$$

$$\epsilon_{\mu\nu\lambda, \sigma\rho\lambda} = \epsilon_{\mu\nu\lambda, \tau\epsilon\lambda}$$

$$k_1, \sigma\rho\lambda + k_2, \sigma\rho\lambda + U_{\epsilon\lambda, \sigma\rho\lambda} = k_1, \tau\epsilon\lambda + k_2, \tau\epsilon\lambda + U_{\epsilon\lambda, \tau\epsilon\lambda}$$

$$\frac{1}{2} m_1 u_1^2 + \frac{1}{2} m_2 0^2 + 0 = \frac{1}{2} m_1 u_1'^2 + \frac{1}{2} m_2 u_2'^2 + \frac{1}{2} k \Delta \ell^2$$

$$u_1^2 + 0 + 0 = u_1'^2 + 2 \cdot 2^2 + 50 \cdot 0,4^2$$

$$u_1^2 = u_1'^2 + 8 + 8$$

$$u_1^2 = u_1'^2 + 16 \quad (2)$$

$$(1) (2) \Rightarrow (u_1' + 4)^2 = u_1'^2 + 16$$

$$u_1'^2 + 8u_1' + 16 = u_1'^2 + 16$$

$$8u_1' = 0 \Rightarrow u_1' = 0 \quad (3)$$

$$(1), (3) \Rightarrow u_1 = 4 \text{ m/s} \quad (4)$$

$$\Delta 2) \left(\frac{dK}{dt} \right)_2 = \sum F_2 u = F_{\epsilon\lambda} \cdot u_2' = 50 \cdot 0,4 \cdot 2 = 40 \text{ J/s} \quad (5)$$

α τρόπος $\frac{dU_{\epsilon\lambda}}{dt} = \left(- \frac{dW_{F_{\epsilon\lambda} 1}}{dt} \right) + \left(\frac{dW_{F_{\epsilon\lambda} 2}}{dt} \right) = - \left(F_{\epsilon\lambda} \cdot u_1' \right) - F_{\epsilon\lambda} u_2'$

$$= F_{\epsilon\lambda} \cdot u_1' - F_{\epsilon\lambda} \cdot u_2' \quad (5) = -40 \text{ J/s}$$

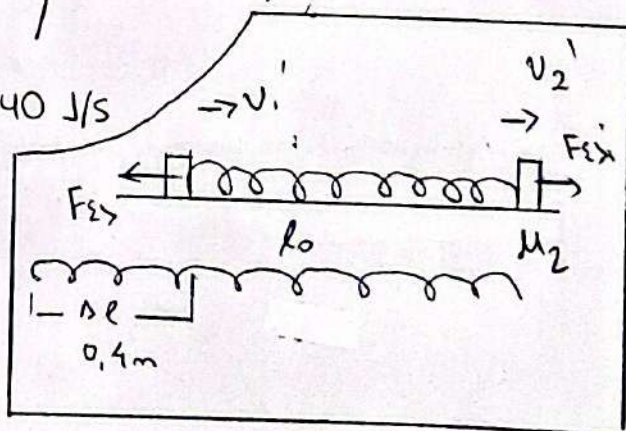
β τρόπος

$$\epsilon_{\mu\nu\lambda} = 6\pi a \partial \epsilon \rho \eta$$

$$U_{\epsilon\lambda} + k_1 + k_2 = 6\pi a \partial \epsilon \rho \eta$$

$$\frac{dU_{\epsilon\lambda}}{dt} + \frac{dk_1}{dt} + \frac{dk_2}{dt} = 0$$

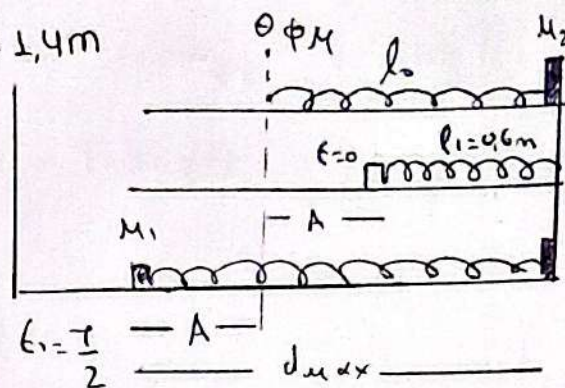
$$\frac{dU_{\epsilon\lambda}}{dt} = - \frac{dk_1}{dt} - \frac{dk_2}{dt} = - \sum F_{\epsilon\lambda} u_1' - \sum F_{\epsilon\lambda} u_2' = - k \ell \cdot u_2' = -40 \text{ J/s}$$



Δ3) Το σώμα Σ1 πραγματοποιεί Α.Α.Τ με πλάτος $A=0,4\text{m}$

$$d_{\max} = \ell_1 + A + A = 0,6 + 0,4 + 0,4 = 1,4\text{m}$$

$$\Delta t = \frac{T}{2} = \frac{1}{2} 2\pi \sqrt{\frac{m_1}{k}} = 0,1\pi\sqrt{2} \text{ sec}$$



Δ4) $\Sigma F_3 = -D_3 x = -\frac{k M_3}{M_1 + M_3} \cdot x$

$$T_{6T} = -\frac{k M_3}{M_1 + M_3} x$$

$$|T_{6T}| = \frac{50 M_3}{1 + M_3} |x|$$

$$|T_{6T}|_{\max} = \frac{50 M_3}{1 + M_3} A = \frac{20 M_3}{1 + M_3}$$

πρέπει

$$\frac{20 M_3}{1 + M_3} \leq \mu_{6T} \cdot N = \mu_{6T} M_3 g$$

$$\frac{20}{1 + M_3} \leq \mu_{6T} \cdot g$$

$$\frac{20}{1 + M_3} \leq \mu_{6T} \cdot 10 = 0,5 \cdot 10 = 5$$

$$\frac{20}{5} \leq 1 + M_3 \Rightarrow 4 \leq 1 + M_3 \Rightarrow \boxed{M_3 = 3\text{kg}}$$

Δ5) $\frac{d\omega T_{6T}}{dt} = T_{6T} \cdot v = -\frac{50 \cdot 3}{1 + 3} x \cdot v = -\frac{150}{4} x \cdot v$

Α.Δ.Ε.Τ $U + K = E_{\text{ταλ}}$

$$\frac{1}{2} 50 x^2 + \frac{1}{2} 40 x v^2 = \frac{1}{2} 50 \cdot 0,4^2 \Rightarrow$$

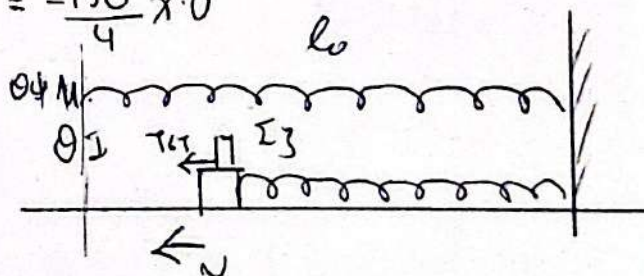
$$50 x^2 + 4 \left(\frac{\sqrt{3}}{2}\right)^2 = 50 \cdot 0,16 \Rightarrow$$

$$50 x^2 + 4 \cdot \frac{3}{2} = 8 \Rightarrow$$

$$50 x^2 = 2 \Rightarrow x = \pm \frac{1}{5} = \pm 0,2\text{m}$$

στην περίπτωση μας $x = 0,2\text{m}$ & $v = -\sqrt{3}/2$

όρα $\frac{d\omega T_{6T}}{dt} = -\frac{150}{4} \cdot 0,2 \left(-\frac{\sqrt{3}}{2}\right) = +7,5 \cdot \frac{\sqrt{3}}{2} \text{ J/s}$



ΘΕΜΑ Ε

9

$$E_1) \sum F_2 = 0 \Rightarrow T_2 = \omega_2 x \Rightarrow T_2 = m_2 g \mu \sin 30 \Rightarrow T_2 = 4 \text{ kg} \cdot g \cdot \frac{1}{2} \Rightarrow T_2 = 2 \text{ kg} \quad (1)$$

τροχαλία $\sum \tau(0) = 0 \Rightarrow T_1 \cdot R - T_2 \cdot r = 0 \Rightarrow T_1 \cdot 2r = T_2 r \Rightarrow T_1 = \frac{T_2}{2}$

$$\Rightarrow \boxed{T_1 = \text{kg}}$$

$$\sum F_1 = 0 \Rightarrow T_1 = \omega_1 + F_{\text{ελ}} \Rightarrow \text{kg} = \text{kg} + F_{\text{ελ}}$$

$$\Rightarrow \kappa \Delta \rho_0 = 0 \Rightarrow \boxed{\Delta \rho_0 = 0}$$

$E_2) \sum F_1 = m_1 a$ Θετική φορά πάνω

$$-\omega_1 - F_{\text{ελ}} + T_1 = m_1 a_1$$

$$T_1 = m_1 a + \omega_1 + F_{\text{ελ}}$$

$$T_1 = 1(-100\pi) + 14g + \kappa \cdot \pi$$

$$T_1 = -100\pi + 150\pi + 10$$

$$\boxed{T_1 = 10 + 50\pi}$$

$\sum F_2 = m_2 a$ Θετική φορά κάτω

$$-T_2 + \omega_2 x = m_2 a_2$$

$$\omega_2 x - m_2 a_2 = T_2$$

$$\boxed{T_2 = 20 - 4a_2}$$

$$\left. \begin{aligned} |a_1| &= \alpha_{\text{γωνία}} = \alpha \cdot R \\ |a_2| &= \alpha_{\text{γωνία}} = \alpha \cdot r \end{aligned} \right\} \frac{|a_1|}{|a_2|} = 2$$

$$\text{όρα } a_2 = \frac{a_1}{2} = -50\pi$$

$$\text{οπότε } 20 - 4(-50\pi) = T_2$$

$$\boxed{T_2 = 20 + 200\pi}$$

$E_3) \text{ Αν τα υήματα λησάρωσαν } T_1 = 0, T_2 = 0$

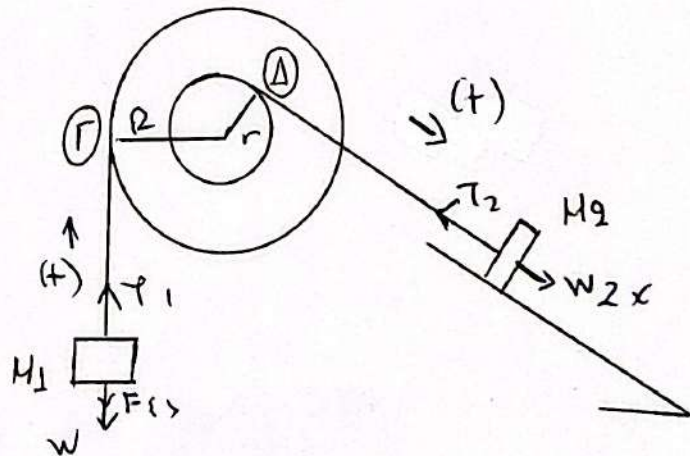
$$10 + 50\pi = 0 \quad \text{και} \quad 20 + 200\pi = 0$$

$$\pi = -0,2 \text{ m}$$

$$\pi = -0,1 \text{ m}$$

$$\text{Αρα } |x_{\text{max}}| = 0,1 \text{ m}$$

$$\text{και } \underline{a_{\text{max}}} = 0,1 \text{ m}$$



$$E4) \textcircled{a} x_2 = \frac{\sqrt{3} \cdot 0,1}{4}$$

$$x_1 = \frac{\sqrt{3} \cdot 0,1}{2}$$

10

ΔΕ.Τ

$$\frac{1}{2} D_1 \pi_1^2 + \frac{1}{2} M_1 v_1^2 = \frac{1}{2} D A^2$$

$$M_1 \omega^2 \left(\frac{\sqrt{3} \cdot 0,1}{2} \right)^2 + v_1^2 = M_1 \omega^2 \cdot 0,1^2$$

$$\frac{3}{4} + v_1^2 = 1 \Rightarrow v_1^2 = \frac{1}{4}, v_1 = \pm \frac{1}{2} \text{ m/s}$$

μεωτεν φαρα $v < 0$ αρα $v = -\frac{1}{2} \text{ m/s}$

$$a_c = \frac{v^2}{R} = 5 \text{ m/s}^2$$

$$a_{En} = |a_n| = 100 \left(\frac{\sqrt{3} \cdot 0,1}{2} \right) = 5\sqrt{3} \text{ m/s}^2$$

$$\alpha_0 = \sqrt{a_c^2 + a_{En}^2} = \sqrt{5^2 + (5\sqrt{3})^2} = \sqrt{5^2 \cdot 4}$$

$$\alpha_0 = 5 \cdot 2 = 10 \text{ m/s}^2$$

$$E4) T_1 = 10 + 50 \left(\frac{0,1}{2} \right) = 12,5 \text{ N}$$

$$\textcircled{b} T_2 = 20 + 200 \frac{0,1}{2} = 30 \text{ N}$$

$$A_x = T_2 \sin 30 = 30 \frac{\sqrt{3}}{2} = 15\sqrt{3} \text{ N}$$

$$A_y = T_2 \cos 30 + T_1 + W_1 = 15 + 12,5 + 17,5 = 45 \text{ N}$$

$$A = \sqrt{45^2 + (15\sqrt{3})^2}$$

$$= \sqrt{15^2 \cdot 9 + 15^2 \cdot 3}$$

$$= \sqrt{15^2 \cdot 12} = 15 \cdot 2\sqrt{2} = 30\sqrt{2} \text{ N}$$

$$E5) \frac{dT_2}{dt} = \frac{d(20 + 200x)}{dt} = 200v = 200(-1/2) = -100 \text{ N/s}$$

